

A WEB-BASED TELEOPERATION FOR AMR FOR ROBOT NAVIGATION CONTROL

A Project report submitted in partial fulfilment of the requirements for the award of degree

of

BACHELOR OF TECHNOLOGY

IN

ELECTRONICS AND COMMUNICATION ENGINEERING

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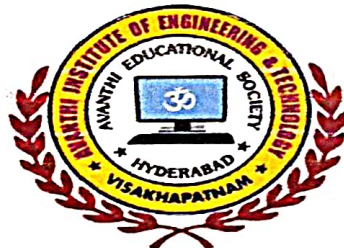
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VIZIANAGARAM)**

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ANAKAPALLI DISTRICT -531113

2020-2024

AVANTHI INSTITUTE OF ENGINEERING AND TECHNOLOGY

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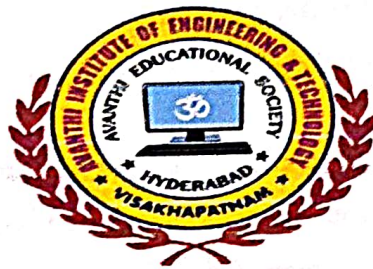
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CERTIFICATE

This is to certify that the program entitled **“A WEB-BASED TELEOPERATION OF AMR FOR ROBOT NAVIGATION”** in partial fulfilment for the degree of Bachelor of technology Department of ELECTRONICS AND COMMUNICATION ENGINEERING at AVANTHI INSTITUTE OF ENGINEERING AND TECHNOLOGY , Makavarapalem , Narsipatnam is an bonafied work carried out by, B.PRASANTHI (20811A0413), M.SRIVANI (20811A0440), A.RENUKA (20811A0403), T.AZAD (20811A0405), Under the guidance and supervision during 2023-2024.


PROJECT GUIDE

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EXTERNAL EXAMINER

ABSTRACT

The “Web-Based Tele-operation for AMR” project introduces a user-friendly interface accessible via web browser, enabling remote control and navigation of Autonomous Mobile Robots (AMRs). Through this interface, users can command AMRs to move, turn, and navigate within their environment in real-time, regardless of their physical location. By empowering remote navigation control, the project enhances the flexibility and accessibility of AMRs in various applications, including logistics, surveillance, and exploration.

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